Meeting with Wilson

Modeling a camera

Rectilinear format (openCV) has this - rectangularizes the image from the curved raw

https://docs.opencv.org/4.x/d9/d0c/group\_\_calib3d.html

https://medium.com/@kennethjiang/calibrate-fisheye-lens-using-opencv-333b05afa0b0

image to help correct raw GPS coordinate reading

Structured Computation

Get Thresholding working (RGB stuff)

Cv.threshold

cv.findContours

Convert to HSV

Feature Matching

* https://datahacker.rs/feature-matching-methods-comparison-in-opencv/

-https://docs.opencv.org/3.4/d5/d6f/tutorial\_feature\_flann\_matcher.html

Mapping:

Implementing ROS:

Rospy

cv.bridge